

Suppression of Continuum Background with Neural Networks for Belle II

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December 19, 2023

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Belle II/SuperKEKB Overview

- $e^+ e^-$ collision experiment at SuperKEKB in Tsukuba, Japan
- \bullet Operation at the $\Upsilon(4S)$ resonance
- Aim for high statistics to enable precision measurements (luminosity goal: $\mathcal{L} = 6 \times 10^{35} \, \text{cm}^{-2} \, \text{s}^{-1}$)



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Belle II/SuperKEKB Overview

 $\mathbf{e} \in \mathbf{e}^+ \mathbf{e}^-$ collision experiment at SuperKEKB in Tsukuba, Japan • Operation at the T(45) resonance • Aim for high statistics to enable precision measurements (luminosity goal: $\mathcal{L} = 6 \times 10^{16} \mathrm{cm}^{-2} \mathrm{s}^{-1}$)



Theoretical Motivation



 $13.93 \pm 0.38 \pm 0.71$

 $10.40 \pm 0.66 \pm 0.60$



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— Theoretical Motivation



- 2. Holds in isospin symmetry limit (equal quark masses) (right?)
- 3. Not exactly = 0, but expected deviation from zero is still much smaller then experimental uncertainties.

heoretical Motivation

$$\begin{split} & 2\mathcal{A}_{CF}(\pi^{0}\mathbf{K}^{+})\frac{B(\pi^{0}\mathbf{K}^{+})}{B(\pi^{-}\mathbf{K}^{+})}\frac{\tau_{\mathbf{k}^{0}}}{\tau_{\mathbf{k}^{+}}} \\ & -\mathcal{A}_{CF}(\pi^{0}\mathbf{K}^{0})\frac{B(\pi^{+}\mathbf{K}^{0})}{B(\pi^{-}\mathbf{K}^{+})}\frac{\tau_{\mathbf{k}^{0}}}{\tau_{\mathbf{k}^{+}}} \\ & -\mathcal{A}_{CF}(\pi^{-}\mathbf{K}^{+})+2\mathcal{A}_{CF}(\pi^{0}\mathbf{K})\frac{B(\pi^{0}\mathbf{K}^{0})}{R(\pi^{-}\mathbf{K}^{+})} \end{split}$$

5 _____V_M^V_M_s____r

- 4. Highlight the B \rightarrow K π decay modes appearing in sum rule.
- 5. Highlight that $B^0 \to K^0 \pi^0$ is measured worst (also as not self tagging)
- 6. NP (particles) could contribute to loops.

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 $B^+ \rightarrow K^+ \pi^0$

 $B^0 \rightarrow K^0 \pi^0$

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 $0.013 \pm 0.027 \pm 0.005$

 $-0.06 \pm 0.15 \pm 0.04$

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Continuum Background





- $e^+e^- \rightarrow q\bar{q}$ where q = u, d, c, s
- dominating background for B decay measurements (other backgrounds easily rejected)
- excess energy results in hadronic iets
- topology distinct from signal decays

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Continuum Background



- 1. Point to the event shape figure.
- 2. Explain uniform $q\bar{q}$ background in resonances figure.

Continuum Suppression

General Idea

Use topological differences to classify signal and background \rightarrow *thrust frames*

Usual Approach	Proposed Approach
 Variables engineered for continuum suppression 	 Low level momentum and decay vertex variables
• BDT for classification	 Attempt to use DNNs, expecting them to excel in extraction of information from low level variables

Past research: Common CS variables augmented with low level variables. Never low level variables exclusively.

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General Idea	
Use topological differences to classify signal	and background
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Continuum Suppression

1. Make sure to explain thrust frames!

2. Momentum/vertex variables in theory should contain all the information of event shape.

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Reconstruction and Data

Chose $B^0 \to K^0_S(\pi^+\pi^-)\pi^0(\gamma\gamma)$ as an example

- Reconstruct charged tracks and calorimeter clusters
- Tracks/clusters not matched to B decay form the *rest of event* (roe)



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-Reconstruction and Data

1. Explain signal thrust/roe thrust using figure on the left

Reconstruction and Data

 $\begin{aligned} \mathsf{Chose} \; \mathsf{B}^0 \to \mathsf{K}^0_S(\pi^+\pi^-)\pi^0(\gamma\gamma) \text{ as an example} \\ \bullet \; \mathsf{Reconstruct charged tracks and calorimeter clusters} \\ \bullet \; \mathsf{Tracks/clusters not matched to B decay form the rest of event (roe) \end{aligned}$



Continuum Suppression Variables

Momentum vector: p, θ_p, φ_p, decay vertex position: d, θ_d, φ_d
Use same number of tracks/clusters from roe as available for signal
→ Fit variables: ΔE, probability density transform (denoted μ)



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Continuum Suppression Variables

- 1. Note that we attempted to use more variables from roe which did not result in a
- significant performance gain
- 2. Explain chosen orders tracks/clusters for variables
- 3. Explain notation (briefly)
- 4. Explain variables that do not fall under the naming scheme
- 5. Explain intuition for polar angle distribution based on antiparallel/random alignment of thrust axes.

Continuum Suppression Variables

u Momentum vector: $p, θ_{pr}, φ_{pr}$ decay vertex position: $d, θ_d, φ_d$ **u** Use same number of tracks/clusters from roe as available for signal → Fit variables: ΔE, probability density transform (denoted µ)



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Classifiers Used

loosted Decision Trees (BTDs)	Deep Neural Networks (DNNs)
 Robust classifiers Give good baseline for expected performance 	 Initial motivation: Possibly better a utilizing information from low level variables → better performance?
. Here as in death honorepresenter tuning	 Turn out to be much more

delicate/difficult to handle Main subject of studies for this thesis

Classifiers Used

Boosted Decision Trees (BTDs)

- Robust classifiers
- Give good baseline for expected performance
- Here no in-depth hyperparameter tuning

Deep Neural Networks (DNNs)

- Initial motivation: Possibly better at utilizing information from low level variables → better performance?
- Turn out to be much more delicate/difficult to handle
- Main subject of studies for this thesis



The Need for Decorrelation



CS with NNs for Belle II 18 12 2023-: The Need for Decorrelation

1. Explain expected shape using left plot.

2. Highlight that fit with observed level of sculpting is clearly impossible.



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Tools(s) for Decorrelation Distance Correlation

- Efficiently estimable correlation metric, capturing also non-linear correlations
- Only one further hyperparameter introduced

Total loss:

$\mathcal{L}_{\mathsf{total}} = \mathcal{L}_{\mathsf{classifier}}(\vec{y}, \vec{y}_{\mathsf{true}}) + \lambda \cdot \mathsf{dCorr}(\vec{z}, \vec{y})$

However tuning still difficult:

- $\bullet\,$ Too large λ degrades performance
- Effectiveness of decorrelation also influenced by other hyperparameters (batch size, network architecture)
- Systematic tuning extremely difficult due to conflicting objectives
- \rightarrow Studies with preliminary hyperparameters to better understand behavior

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Efficiently estimable correlation metric, capturing also non-linear correlations
 Only one further hyperparameter introduced

 $\mathcal{L}_{\text{total}} = \mathcal{L}_{\text{classifier}}(\vec{y}, \vec{y}_{\text{true}}) + \lambda \cdot \text{dCorr}(\vec{z}, \vec{y})$

However tuning still difficult:

Fools(s) for Decorrelation

- Too large A degrades performance
 Effectiveness of decorrelation also influenced by other hyperparameters (hatch size rotoock-architecture)
 Systematic tuning extremely difficult due to conflicting objectives
 Studies with releminary hyperparameters to better understand bahavior
- 1. Also mention that adversary networks have been implemented, but could not be sufficiently tuned for this thesis.
- 2. Explain symbols in the equation!
- 3. Mention that classifier loss is binary cross-entropy.
- 4. Explain the conflicting objectives of best performance and effective decorrelation (problem: performance always better for correlated classifier).

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Monitoring DNN Training Evolution of ΔE (Background) Distribution

- Preliminary hyperparameters with different values for λ (0, 1, 1.8)
- Achieved decorrelation still not satisfactory
- Sculpting (partially suppressed) suddenly starts after sufficient number of epochs

projection at without DisCo best epoch epoch 51 0.2 · 0.0 --0.2 -50 60 0 200 with DisCo, still partially sculpted epoch 199 > 0.2 2 🚊 0.0 $\overline{d}_{-0.2}$ 125 150 175 200 100 with DisCo, suppressed sculpting 0.20.0Ē. -0.225 125 150 175 0 100

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—Monitoring DNN Training

- 1. Highlight that after sufficient training (or epochs), correlation (more or less suddenly) starts \rightarrow decorrelation is unstable.
- 2. Mention that here the goal was to reach lower sculpting than BDT in hope of this improving fit quality (i.e. lowering the statistical uncertainties). Thus the best decorrelation is still not satisfactory.
- 3. Distributions are normalized at each epoch!



1.8)

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Choice of Hyperparameters

	prelim. value	final value	description
n_{layers}	5	5	number of layers
$n_{\sf neurons,0}$	100	100	1st dense layer neurons
$n_{neurons,1}$	100	100	2nd dense layer neurons
$n_{neurons,2}$	4	6	3rd dense layer neurons
$n_{ m neurons,3}$	100	100	4th dense layer neurons
$n_{neurons,4}$	100	100	5th dense layer neurons
weight decay	0.000142	0.000142	Weight decay for AdamW
learning rate	0.002	0.015	learning rate
dCorr on bgn	True	True	choice to compute dCorr on only background events
λ	1.8	2	scale of dCorr in total loss
s_{λ}	7.5	7.5	scale factor for λ when dCorr computed on bgn only
batch size	2048	16384	number of events in a minibatch

 \rightarrow In the following DNN with applied decorrelation and final hyperparameters is referred to as DisCoDNN

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Choice of Hyperparameters

	prelim. value	final value	description
Dieen	5	5	number of layers
Common d	100	100	1st dense layer neurons
Dearson, i	100	100	2nd dense layer neurons
Common 2	4	6	3rd dense layer neurons
General I	100	100	4th dense layer neurons
Department of	100	100	5th dense layer neurons
weight decay	0.000142	0.000142	Weight decay for AdamW
learning rate	0.002	0.015	learning rate
dCorr on bgn	True	True	choice to compute dCorr on only background event
λ	1.5	2	scale of dCorr in total loss
f.,	7.5	7.5	scale factor for λ when dCorr computed on ben only
batch size	2048	10304	number of events in a minibatch

1. Highlight the "unusual" hyperparameters: Large batch size, bottleneck architecture

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Performance Evaluation Classifier Outputs, ROC Curves

- Output distributions shaped as expected
- Clear performance drop when applying decorrelation
- Maximum signal efficiency lower for DisCoDNN







Performance Evaluation

1. Note that prelim. DisCoDNN only shown as reference for *not good* output distribution.

ΔE and μ after Continuum Suppression

Cuts always chosen for 90% signal efficiency

 ΔE :

 μ :

- Effective decorrelation with DisCoDNN
- Remaining (but acceptable) sculpting for BDT
 - $\rightarrow\,$ Could further investigate decorrelation for BDTs
- Overall better background suppression with BDT at same signal efficiency
- Shapes unaffected by decorrelation

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• Reasonably flat signal contributions



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 $\Box \Delta E$ and μ after Continuum Suppression



1. Maybe mention how cut positions were determined/that they were determined using an appropriate procedure.

Fits on MC



 $\rightarrow 8.90\%$ stat. error

-----<u>______</u> ************** 0.2 0.4 0.6

 $\rightarrow 8.14\%$ stat. error

• Both fits of decent quality

- No real gain from using DNN
- BDT with exclusively engineered variables gives $\sim 9.7\%$ stat. error

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1. Shapes fixed on MC, final fit of only yields

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0.8

Classifier Generalizability

- Apply to topologically similar control channel $B^0 \rightarrow \overline{D}^0(K^+\pi^-)\pi^0(\gamma\gamma)$
 - All classifiers fail to identify signal
 - Surprisingly good continuum suppression possible with very loose cuts
 - DNN without decorrelation fails spectacularly





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Classifier Generalizability



- 1. Mention that this demonstrates the problem of generalizability!
- 2. Note that DNN (no DisCo) seems *not* to just "compute" or estimate ΔE and then more or less cut on that, as $B\overline{B}$ background remains!
- 3. Possibly the correlations are then what allows the DNN to sculpt ΔE . This would make sense as DisCoDNN does not really rely on correlations.

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³ 0.85

2 0.80

₹ 0.75 ·

0.65 -

DisCoDNN (AUC = 0.9924)
 DNN (no DisCo) (AUC = 0.9953)
 BDT (AUC = 0.9952)
 DisCoDNN CC (AUC = 0.9785)

— DNN (no DisCo) CC (AUC = 0.9674)

0.75

0.80 signal efficienc

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0.95

16/17

0.90

0.85

Conclusion & Outlook

- Introduced set of low level continuum suppression variables
- Prepared BDT and DNNs using introduced variables, expecting DNN to profit from those
- DNNs require decorrelation, which most likely limits their performance
- Fits on MC show similar accuracies for BDT/DNN but slighly better than BDT with common CS variables
- \rightarrow Low level CS variables could reduce statistical errors but further investigation (e.g. systematics etc.) needed for final judgement

For the Future

- Study influence of single variables on sculpting (to possibly exclude them)
- Impact on performance with alternative decorrelation method (e.g. adversarial networks)
- Application of similar decorrelation to BDT
- Application within a fully fledged analysis (including systematics etc.)

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Conclusion & Outlook

· Prenared RDT and DNNs using introduced variables, expecting DNN to profit from those DNNs require decorrelation, which most likely limits their performance # Fits on MC show similar accuracies for BDT/DNN but slighly better than BDT with common CS variables Low level CS variables could reduce statistical errors but further investigation (a systematics etc.) needed for final judgement

· Study influence of single variables on sculpting (to possibly exclude then a Impact on performance with alternative decorrelation method (e.e. adversarial netwo Application of similar decorrelation to BDT Application within a fully fiedded analysis (including systematics etc.)

1. In fact the sculpting also happens with only *engineered* variables. It's just that so far everyone always used BDTs which are not subject to that issue.



Data Samples

- Generic (run independent) MC ($q\bar{q}$ where $q = u, d, s, c \& B\overline{B}$): 1 ab⁻¹
- Pure signal MC for signal channel and control channel: 4 × 10⁶ and 2 × 10⁶ events produced resulting in 1019638 and 523183 reconstructed events respectively
 Physics data: 361.65 fb⁻¹
- Off-resonance generic MC ($q\bar{q}$ where q = u, d, s, c): 169.328 fb⁻¹
- Off-resonance data: 42.28 fb^{-1}

MC Modeling

- Problems with the available samples ($au^- au^+$, momentum corrections) remain
- MC modeling overall not bad, considering the above
- $\rightarrow\,$ Further investigation needed for final judgment

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 $\begin{array}{l} \bullet \mbox{ Generic (nn independent)) MC (q\bar{q} \mbox{ where } q=u,d,s,c,L & B[1]: 12b^{-1} \\ \bullet \mbox{ Pars is goal MC for signal channel and control channel. 4 : 10^6 and 2 : 11^6 events$ $produced resulting in 1019(58) and the resonance of the two resonance is respectively \\ \bullet \mbox{ Physical data: 361:56}^{-1} \\ \bullet \mbox{ Off-resonance model. MC (qd) where } q=u,d,s,c]: 169.328\,{\rm fb}^{-1} \\ \bullet \mbox{ Off-resonance data: 42:28\,{\rm fb}^{-1} \end{array}$

• Problems with the available samples ($\tau^- \tau^+$, momentum corrections) remain • MC modeling overall not bad, considering the above \rightarrow Further investigation needed for final judgment

Continuum Suppression Variables All Input Variables

Δz	$R(\cos(\theta_p^{+s0}))$	$R(\phi_p^{0s0})$	$S(\cos(\theta_p^{-s0}))$	$S(\phi_d^{-r0})$	$S(p^{+s0})$
$\cos(\theta_{SR})$	$R(\cos(\theta_d^{-r0}))$	$R(\phi_p^{0s1})$	$S(\cos(\theta_p^{+r0}))$	$S(\phi_d^{-s0})$	$S(\phi_p^{0r0})$
$\cos(\theta_{Sz})$	$R(\cos(\theta_d^{-s0}))$	$R(\phi_p^{-r0})$	$S(\cos(\theta_p^{+s0}))$	$S(\phi_d^{+r0})$	$S(\phi_p^{0r1})$
$M_{ m bc}^{\prime}$	$R(\cos(\theta_d^{+r0}))$	$R(\phi_p^{-s0})$	$S(\cos(\theta_d^{-r0}))$	$S(\phi_d^{+s0})$	$S(\phi_p^{0s0})$
$R(\cos(\theta_p^{0r0}))$	$R(\cos(\theta_d^{+s0}))$	$R(\phi_p^{+r0})$	$S(\cos(\theta_d^{-s0}))$	$S(p^{0r0})$	$S(\phi_p^{0s1})$
$R(\cos(\theta_p^{0r1}))$	$R(\phi_d^{-r0})$	$R(\phi_p^{+s0})$	$S(\cos(\theta_d^{+r0}))$	$S(p^{0r1})$	$S(\phi_p^{-r0})$
$R(\cos(\theta_p^{0s0}))$	$R(\phi_d^{-s0})$	$S(\cos(\theta_p^{0r0}))$	$S(\cos(\theta_d^{+s0}))$	$S(p^{0s0})$	$S(\phi_p^{-s0})$
$R(\cos(\theta_p^{0s1}))$	$R(\phi_d^{+r0})$	$S(\cos(\theta_p^{0r1}))$	$S(d^{-r0})$	$S(p^{0s1})$	$S(\phi_p^{+r0})$
$R(\cos(\theta_p^{-r0}))$	$R(\phi_d^{+s0})$	$S(\cos(\theta_p^{0s0}))$	$S(d^{-s0})$	$S(p^{-r_0})$	$S(\phi_p^{+s0})$
$R(\cos(\theta_p^{-s0}))$	$R(\phi_p^{0r0})$	$S(\cos(\theta_p^{0s1}))$	$S(d^{+r0})$	$S(p^{-s0})$	-
$R(\cos(\theta_p^{+r0}))$	$R(\phi_p^{0r1})$	$S(\cos(\hat{\theta_p^{-r0}}))$	$S(d^{+s0})$	$S(p^{+r0})$	

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Continuum Suppression Variables

NUUI Varia	m Suppres	sion Variat	bles			
	Δ.	$R(\cos(\theta_{a}^{+s0}))$	$R(\phi_{\pi}^{0.0})$	$S[cos(\theta_{a}^{-s0}))$	$S(\phi_{4}^{-r0})$	$S(p^{\pm s2})$
	$cos(\theta_{AB})$	$R(cos(\theta_d^{-r-k}))$	$R(\phi_{x}^{0+1})$	$S[cos(\theta_{n}^{+r0}))$	$S(\phi_A^{-n0})$	$S(\phi_{\alpha}^{0re})$
	$cos(\theta_{Sx})$	$R(cos(\theta_{d}^{-s0}))$	$R(\phi_{\mu}^{-\alpha})$	$S(cos(\theta_{\mu}^{3,a0}))$	S(64")	$S(\phi_{g}^{0r1})$
	Mar	$R(cos(\theta_d^{1+0}))$	$R(\phi_{\mu}^{-ab})$	$S[cos(\theta_d^{-r0}))$	$S(\phi_{4}^{+ab})$	$S(\phi_{\mu}^{\text{Dati}})$
	$B(cos(\theta_{E-}^{lock}))$	$R(cos(\theta_d^{\pm a0}))$	$R(\phi_{g}^{+r_{0}})$	$S(cos(\theta_d^{-s0}))$	$S(p^{0+0})$	$S(\phi_{\mu}^{0u1})$
	$B(cos(\theta_{g}^{trv}))$	$R(\phi_d^{(n)})$	$R(\phi_p^{+m})$	$S(cos(\theta_d^{+1}))$	$S(p^{nr*})$	$S(\phi_{\mu}^{-ra})$
	$B(cos(\theta_{E}^{cost}))$	$R(\phi_d^{-m})$	$S(cos(\theta_{E}^{orv}))$	$S(cos(\theta_d^{+sn'}))$	$S(p^{nm})$	$S(\phi_g^{-arr})$
	$B(cos(\theta_{p}^{tax}))$	$R(\phi_d^{(1)})$	$S(\cos(\theta_{E,c}^{(V^{*})}))$	$S(d^{-ra})$	S(p ¹¹¹)	$S(\phi_{2}^{+10})$
	$B(cos(\theta_{\mu}^{-1}))$	$B(\phi_d^{-})$	$S(cos(\theta_{B}^{-}))$	S(4 ⁻¹¹)	S(p)	S(0,)
	$B(cos(\theta_{g_{-n}}^{-s0}))$	$R(\phi_{E-1}^{evv})$	$S(\cos(\theta_{p}^{(nex})))$	$S(d^{+ra})$	S(p)	
	$B(cos(\theta_p^{+rv}))$	$R(\phi_{\mu}^{-1})$	$S[\cos(\theta_{\mu}^{-10})]$	$S(d^{+-1})$	$S(p^{+m})$	

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Neural Network Architecture and Training

Network Architecture:

- Blocks of dense, activation function and batch normalization layers (# layers = # blocks)
- Initial batch normalization to normalize raw input values
- Final activation mapped to (0, 1)by sigmoid function

DNN Training:

- AdamW optimizer (implements weight decay as regularization)
- Fixed learning rate





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-Neural Network Architecture and Training

Neural Network Architecture and	nd Training
Network Architecture: • Bicsks of denne, activation fenctions and batch nermilation layers (# layers = # blocks) • Initial batch enrollitation to normilate raw input velows • Final activation mapped to (0, 1) by sigmoid function DUN Taining: • AdamV optimize (implements wight deay are regularization) • Fixed learning rate	

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Data Samples for Training

• Samples should contain same number of signal and background events to avoid bias towards either type

- Samples for training and evaluation of performance during as well as after training should be disjoint
- ightarrow Combine $q\bar{q}$ and $B^0 \rightarrow K^0_S(\pi^+\pi^-)\pi^0(\gamma\gamma)$ events from available MC samples



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Data Samples for Training



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Monitoring DNN Training Coincidence of dCorr Increase and Sculpting



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Monitoring DNN Training Evolution of Loss



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1. Talk about intuition of *barrier* in parameter space. DisCo appear to introduce barrier but never really plane the global (correlated) minimum.

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Choosing Continuum Suppression Cuts



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Choosing Continuum Suppression Cuts



Choosing Continuum Suppression Cuts



Fits on MC Fit Results Table

	signal	$q\overline{q}$	$B\overline{B}$
true yield DisCoDNN	318	3313	71
true yield BDT	321	2134	75
yield DisCoDNN	310.6 ± 28.3	3343 ± 39	49.30 ± 31.28
yield BDT	337.5 ± 26.1	2149 ± 35	43.52 ± 27.83
rel. fit error DisCoDNN in %	8.902	1.178	44.06
rel. fit error BDT in %	8.144	1.626	37.1
rel. true error DisCoDNN in $\%$	2.335 ± 8.902	0.897 ± 1.178	30.57 ± 44.06
rel. true error BDT in $\%$	5.133 ± 8.144	0.710 ± 1.626	41.97 ± 37.10
pull DisCoDNN in σ	-0.2623	0.7619	-0.6937
pull BDT in σ	0.6302	0.4367	-1.131

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Fits on MC Fit Results Table

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pull DisCoDNN in a	-0.2623	0.7619	-0.6937
pull BDT in a	0.6302	0.4367	-1.131

Classifier Performance Stability & Input Variable Correlations

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Classifier Performance Stability & Input Variable Correlations



Bootstrapping

Models fluctuations of occurrences of event types, not numerical fluctuations
All classifiers remain reasonably stable

Uncorrelated Toys

- Do not model correlations, as nearly impossible
- Classifiers that do not significantly sculpt ΔE barely utilize correlations between input variables



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